

# Performance and Stability Analysis of the Task Assignment based on Guessing Size Routing Policy

Josu Doncel

University of the Basque Country, UPV/EHU

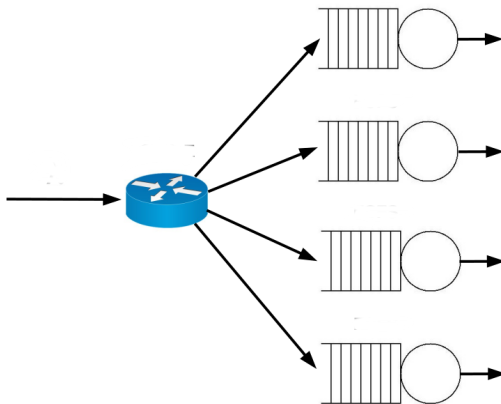
*joint work with E. Bachmat and H. Sarfati (Ben-Gurion University)*

October 22, 2019

# Parallel-Server Systems

K homogeneous FIFO queues

Poisson arrivals



Question?

How to balance the load optimally?

# Application

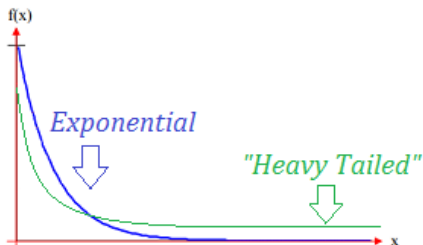


# Heavy-tailed distribution

A small fraction of jobs make up the half of the load

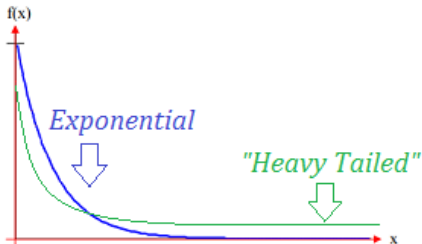
# Heavy-tailed distribution

A small fraction of jobs make up the half of the load



# Heavy-tailed distribution

A small fraction of jobs make up the half of the load



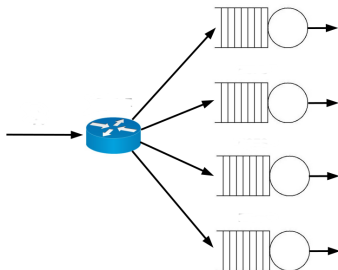
Example: Bounded Pareto  $(1, r, \alpha)$

$$f(s) = \frac{\alpha s^{-\alpha-1}}{1 - r^{-\alpha}}$$

# Known optimality results

JSQ: each incoming job is sent to the server with less number of jobs

Po2: pick  $d$  servers at random  $\Rightarrow$  JSQ



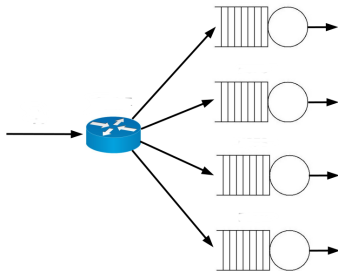
## Disadvantage

Many observations  $\Rightarrow$  Not practical

# Open-loop Routing Policies

## Heavy-tailed: bad performance

- Round-Robin
- Random Splitting

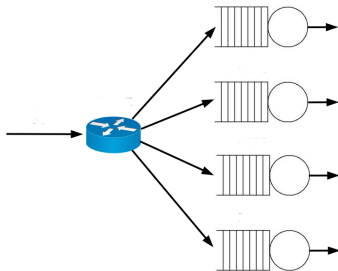




# Open-loop Routing Policies

## Heavy-tailed: bad performance

- Round-Robin
- Random Splitting



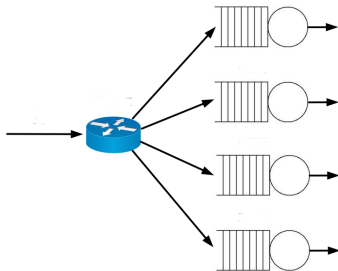
## Heavy-tailed: good performance

- SITA: job duration knowledge

# Open-loop Routing Policies

## Heavy-tailed: bad performance

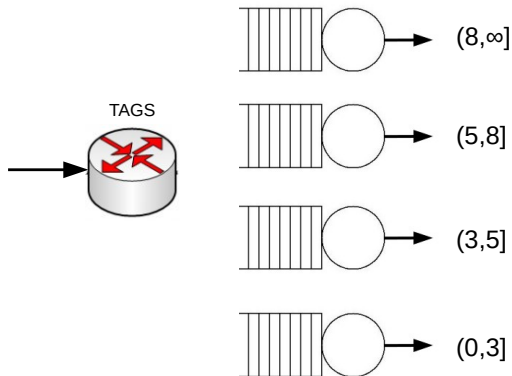
- Round-Robin
- Random Splitting



## Heavy-tailed: good performance

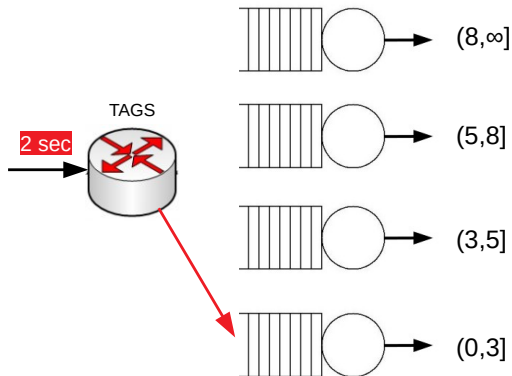
- SITA: job duration knowledge
- Task Assignment with Guesing Size (TAGS)

# TAGS Policy<sup>1</sup>



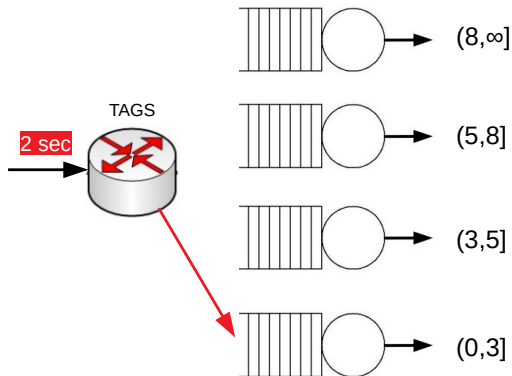
<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

# TAGS Policy<sup>1</sup>



<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

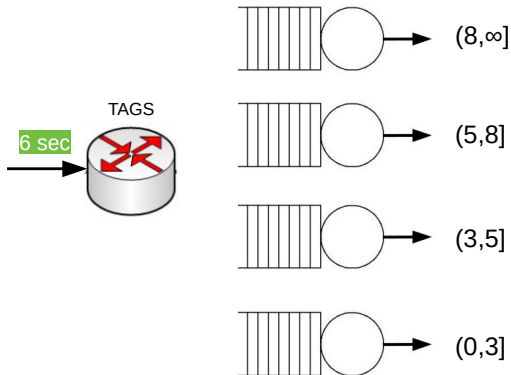
# TAGS Policy<sup>1</sup>



Waiting time:  $W_1$

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

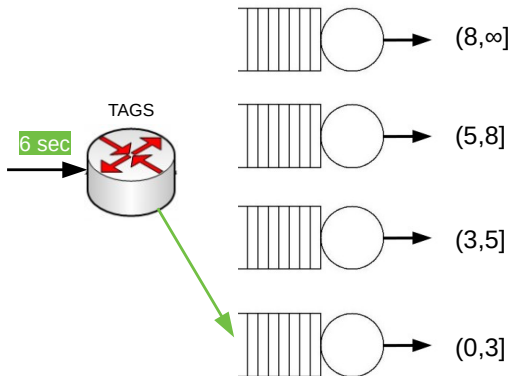
# TAGS Policy<sup>1</sup>



Waiting time:  $W_1$

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

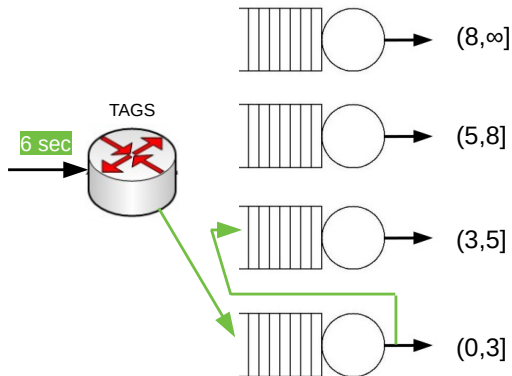
# TAGS Policy<sup>1</sup>



Waiting time:  $W_1$

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

# TAGS Policy<sup>1</sup>

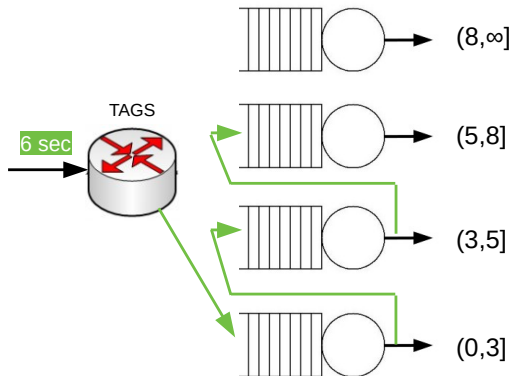


Waiting time:  $W_1$

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.



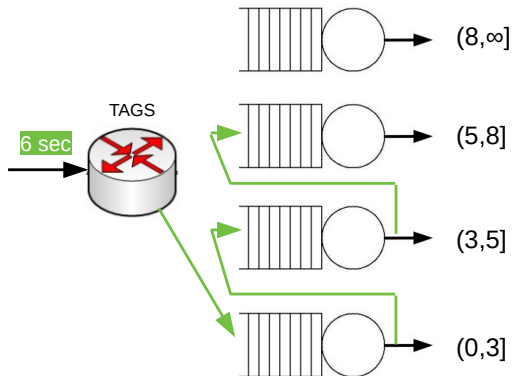
# TAGS Policy<sup>1</sup>



Waiting time:  $W_1$

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

# TAGS Policy<sup>1</sup>



Waiting time:  $W_1$



Waiting time:  $W_1 + 3 + W_2 + 5 + W_3$

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. *J. of the ACM*, 2002.

## Advantages

- No signaling
- Heavy-tail: good performance
- Durations unknown

---

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. [J. of the ACM](#), 2002.  

## Advantages

- No signaling
- Heavy-tail: good performance
- Durations unknown

## Summary of contributions

- 1 Stability
- 2 Optimal performance
- 3 (Bounded) Pareto distribution
  - Comparison with SITA
  - Optimal performance analysis

---

<sup>1</sup>M. Harchol-Balter. Task assignment with unknown duration. [J. of the ACM](#), 2002.

## Advantages

- No signaling
- Heavy-tail: good performance
- Durations unknown

## Summary of contributions

- 1 **Stability**
- 2 Optimal performance
- 3 (Bounded) Pareto distribution
  - Comparison with SITA
  - Optimal performance analysis

## Proposition

Let  $\rho = \lambda\mathbb{E}[X]$ . The TAGS system is stable if and only if

$$\rho < \frac{\mathbb{E}[X]}{M(X)}$$

where  $M(X) = \sup_s s(1 - F(s))$ .

$\Rightarrow$  Critical load  $\rho_{crit}(X)$

## Proposition

Let  $\rho = \lambda \mathbb{E}[X]$ . The TAGS system is stable if and only if

$$\rho < \frac{\mathbb{E}[X]}{M(X)}$$

where  $M(X) = \sup_s s(1 - F(s))$ .

$\Rightarrow$  Critical load  $\rho_{crit}(X)$

## Proposition

Let  $X$  be a distribution in  $[1, r]$

$$\rho_{crit}(X) \leq 1 + \log r.$$

## Bounded Pareto $(1, r, \alpha)$

If  $\alpha \neq 1$ ,

$$\rho_{crit} = (1 - r^{\alpha-1})(1 - \alpha)^{-1/\alpha}.$$

If  $\alpha = 1$

$$\rho_{crit} = \frac{r \log r}{r - 1}.$$



## Bounded Pareto $(1, r, \alpha)$

If  $\alpha \neq 1$ ,

$$\rho_{crit} = (1 - r^{\alpha-1})(1 - \alpha)^{-1/\alpha}.$$

If  $\alpha = 1$

$$\rho_{crit} = \frac{r \log r}{r - 1}.$$

## Tight distribution

$f(x) = 1/x^2$ , for  $x \in [1, r]$

$\Rightarrow$  Dirac delta at  $r$  with mass  $r^{-1}$

## Advantages

- No signaling
- Heavy-tail: good performance
- Durations unknown

## Summary of contributions

- 1 Stability
- 2 **Optimal performance**
- 3 (Bounded) Pareto distribution
  - Comparison with SITA
  - Optimal performance analysis

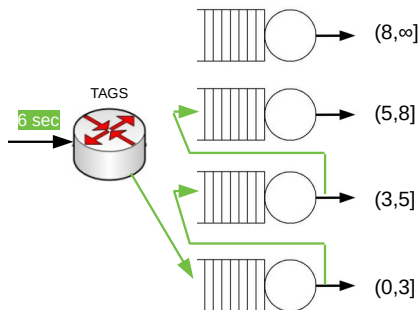
# Bound of the Optimal Performance

## Proposition

Let  $s^{que}$  be the vector of cutoffs that minimizes the maximum mean queue length of the servers. Then, in a system with  $h$  hosts,

$$\mathbb{E}[W(s^{que})] \leq h\mathbb{E}[W^*] + \mathbb{E}[X](h - 1)$$

⇒ Upper-bound of  $\mathbb{E}[W(s^{que})]$ .



## Advantages

- No signaling
- Heavy-tail: good performance
- Durations unknown

## Summary of contributions

- 1 Stability
- 2 Optimal performance
- 3 **(Bounded) Pareto distribution**
  - Comparison with SITA
  - Optimal performance analysis

# Bounded Pareto $(1, r, \alpha)$

## Assumption

Poisson arrivals to all the servers

⇒ Accuracy validation (over-estimation) numerically

# Bounded Pareto $(1, r, \alpha)$

## Assumption

Poisson arrivals to all the servers

$\Rightarrow$  Accuracy validation (over-estimation) numerically

Let  $\rho = \lambda \mathbb{E}[X]$ . When  $r \rightarrow \infty$  and  $\rho < 1$

## Proposition

The mean waiting time in a TAGS system with optimal cutoffs is at most two times larger than the mean waiting time of a SITA system with optimal cutoffs.

# Bounded Pareto $(1, r, \alpha)$

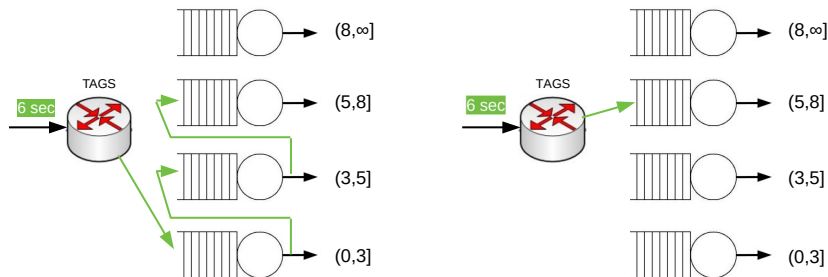


# Bounded Pareto $(1, r, \alpha)$

Let  $\rho = \lambda \mathbb{E}[X]$ . When  $r \rightarrow \infty$  and  $\rho < 1$

## Proposition

The mean waiting time in a TAGS system with optimal cutoffs is at most two times larger than the mean waiting time of a SITA system with optimal cutoffs.



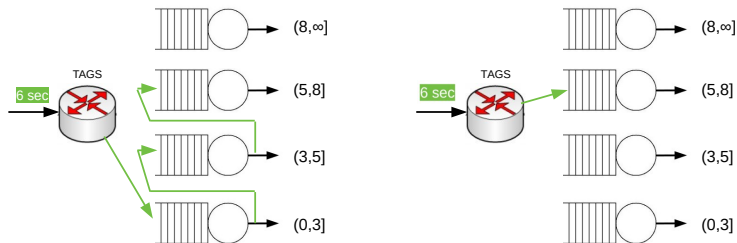


# Bounded Pareto $(1, r, \alpha)$

Let  $\rho = \lambda \mathbb{E}[X]$ . When  $r \rightarrow \infty$  and  $\rho < 1$

## Proposition

The mean waiting time in a TAGS system with optimal cutoffs is at most two times larger than the mean waiting time of a SITA system with optimal cutoffs.



Penalty for not knowing the duration of the jobs is **at most 2**

# Bounded Pareto $(1, r, \alpha)$ when $\rho > 1$

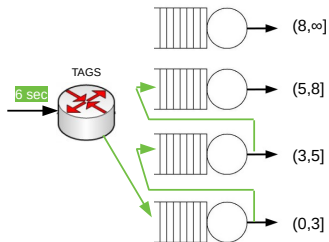
Big performance difference (stable?)

# Bounded Pareto $(1, r, \alpha)$ when $\rho > 1$

Big performance difference (stable?)

$\tilde{h} = h - i + 1$ : number of spare servers

$\Rightarrow i$ : minimum number of servers for stability

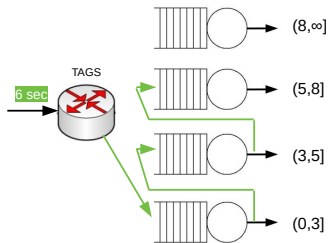


# Bounded Pareto $(1, r, \alpha)$ when $\rho > 1$

Big performance difference (stable?)

$\tilde{h} = h - i + 1$ : number of spare servers

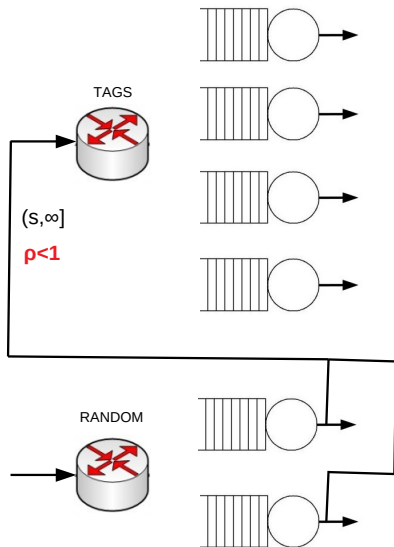
$\Rightarrow i$ : minimum number of servers for stability



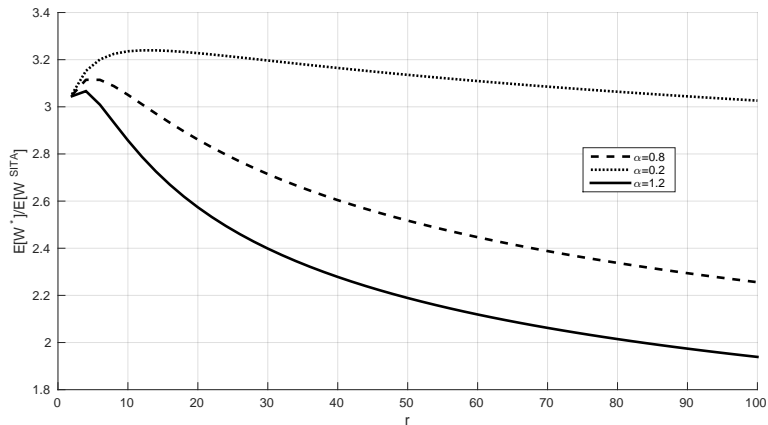
## Proposition

When  $r \rightarrow \infty$  and  $\rho > 1$ , the order of magnitude of the optimal mean waiting time of TAGS depends on  $\tilde{h}$  and not on  $h$ .

# T+W Policy



# Numerical Experiments with $r < \infty$ and $\rho = 0.5$



## Advantages of TAGS

- No signaling
- Heavy-tail: good performance
- Durations knowledge not required

## Our contributions

- 1 Stability
- 2 Optimal performance
- 3 (Bounded) Pareto distribution
  - Comparison with SITA
  - Optimal performance analysis

## Advantages of TAGS

- No signaling
- Heavy-tail: good performance
- Durations knowledge not required

## Summary of contributions

- 1 Stability  $\Rightarrow$  Critical load
- 2 Optimal performance
- 3 (Bounded) Pareto distribution
  - Comparison with SITA
  - Optimal performance analysis



## Advantages of TAGS

- No signaling
- Heavy-tail: good performance
- Durations knowledge not required

## Our contributions

- 1 Stability  $\Rightarrow$  Critical load
- 2 Optimal performance  $\Rightarrow$  Bounds
- 3 (Bounded) Pareto distribution
  - Comparison with SITA
  - Optimal performance analysis

## Advantages of TAGS

- No signaling
- Heavy-tail: good performance
- Durations knowledge not required

## Our contributions

- 1 Stability  $\Rightarrow$  Critical load
- 2 Optimal performance  $\Rightarrow$  Bounds
- 3 (Bounded) Pareto distribution
  - Comparison with SITA  $\Rightarrow$  when  $\rho < 1$
  - Optimal performance analysis  $\Rightarrow$  when  $\rho > 1$

## TODOs in our model

Non-asymptotic analysis and comparison with other policies

## TODOs in our model

Non-asymptotic analysis and comparison with other policies

## Extensions to energy networks

EPN

On-off servers

## TODOs in our model

Non-asymptotic analysis and comparison with other policies

## Extensions to energy networks

EPN

On-off servers

**THANKS**